

madk_pp_protocol.h

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1Â /***** 2Â * Company: Verifone 3Â *
Author: GSS R&D Germany 4Â * Content: SDI-Server 5Â
*****/ 6Â #ifndef _MADK_PP_PROTOCOL_H_ 7
Â #define _MADK_PP_PROTOCOL_H_ 8Â 9Â #include <vector> 10Â #include <string> 11Â #include <pthread.h> 12Â 14
Â struct madk_pp_prot_loader; 16Â struct ProtStatus; 17Â struct ConnectInfo; 18Â struct TcpInfo; 19Â struct
UdsInfo; 20Â 23Â class madk_pp_prot 24Â { 25Â public: 26Â 27Â enum ProtocolState 28Â { 29Â PS_Stopped = 0,
30Â PS_Running = 1, 31Â PS_Aborted = 2 32Â }; 33Â 34Â enum AbortState 35Â { 36Â AS_NotAborted = 0, 37Â
AS_AbortIdle = 1, 38Â AS_ConnectionLost = 2 41Â }; 42Â 43Â private: 44Â pthread_t proto_thread; 45Â
pthread_mutex_t mutex; 46Â pthread_cond_t cond; 47Â std::vector<unsigned char> cmdbuf; 48Â char prot_type; 50
Â unsigned msg_id; 51Â unsigned msg_id_payment; 52Â unsigned msg_id_nested; 53Â enum ProtocolState
prot_state; 54Â bool cmd_active; 55Â bool nested_cmd; 56Â enum AbortState aborted; 57Â unsigned cmd_counter;
59Â struct madk_pp_prot_loader *lib; 63Â enum CommandType 64Â { 65Â Cmd_Any = 0, 66Â Cmd_Abort = 1, 67Â
Cmd_LockPayment = 2, 69Â Cmd_ResetLink = 3, 72Â Cmd_Check4Update = 4, 73Â Cmd_ExtButton = 5, 74Â
Cmd_EnvCbResponse = 6, 75Â Cmd_CtrlCbResponse = 7, 76Â Cmd_TrgrCbResponse = 8, 77Â Cmd_PaymentNotificationCb
= 9 78Â }; 80Â enum RequestType 81Â { 82Â Request_None = 0, 83Â Request_EMV = 1, 84Â Request_Ctrl = 2, 85
Â Request_Trgr = 3 86Â }; 87Â RequestType req_type; 88Â bool recovery_mode; 89Â bool busy; 90Â bool
cancelled; 91Â bool unlock_payment_pending; 94Â void *main_handle; 101Â void *busy_handle; 104Â static
madk_pp_prot *obj; // singleton 105Â 106Â // disable calling copy constructor and assignment operator 107Â
madk_pp_prot(const madk_pp_prot &); 108Â void operator=(const madk_pp_prot &); 109Â #if __cplusplus >= 201103L
// since C++11 also forbid usage of move 110Â madk_pp_prot(const madk_pp_prot&&); 111Â madk_pp_prot&
operator=(madk_pp_prot&&); 112Â #endif 113Â 114Â // disable constructor and force caller to use getInstance()
115Â madk_pp_prot(); 118Â virtual ~madk_pp_prot(); 119Â 122Â static void *run(void *data); 123Â 130Â
static enum CommandType getCommandType(const unsigned char *cmd, unsigned size); 131Â 136Â static bool
isCallbackResponse(const enum CommandType cmd); 137Â 145Â bool _poll(int timeout_msec); 146Â 155Â bool
_receive(std::vector<unsigned char> &cmd, int timeout_msec); 156Â 163Â bool _send(void *handle, const unsigned
char *cmd, unsigned size, char protType, unsigned msgId) const; 164Â 171Â int _get_connection_type(void
*handle); 172Â public: 173Â 176Â static madk_pp_prot *getInstance(); 177Â 181Â inline struct
madk_pp_prot_loader *loader() 182Â { 183Â return lib; 184Â }; 185Â 192Â bool poll(int timeout_msec = -1);
193Â 201Â bool receive(std::vector<unsigned char> &cmd, int timeout_msec = -1); 202Â 211Â bool abort();
212Â 224Â bool send(const unsigned char *cmd, unsigned size); 225Â 227Â inline bool send(const
std::vector<unsigned char> &cmd) 228Â { 229Â return send(cmd.size() > 0 ? &cmd[0] : 0, cmd.size()); 230Â }
231Â 243Â bool command(const unsigned char *cmd, unsigned size); 244Â 261Â bool request(const unsigned char
*cmd, unsigned size); 262Â 264Â inline bool request(const std::vector<unsigned char> &cmd) 265Â { 266Â
return request(cmd.size() > 0 ? &cmd[0] : 0, cmd.size()); 267Â } 268Â 281Â bool
rcv_response(std::vector<unsigned char> &response, int timeout_msec = -1); 282Â 306Â bool set_busy(bool flag,
bool cmd_ctx = true); 307Â 311Â bool loadAcl(); 312Â 314Â enum CMDActiveType 315Â { 316Â CMD_None = 0,
317Â CMD_Active = 1, 318Â CMD_Nested = 2 319Â }; 323Â inline enum CMDActiveType command_active() const 324Â
{ 325Â if (cmd_active) 326Â { 327Â if (nested_cmd) 328Â { 329Â return CMD_Nested; 330Â } 331Â 332Â
return CMD_Active; 333Â } 334Â 335Â return CMD_None; 336Â } 337Â 341Â bool start(); 342Â 346Â void
stop(); 347Â 350Â void setRecoveryMode(bool on_off); 351Â 354Â inline enum ProtocolState
get_protocol_state() const 355Â { 356Â return prot_state; 357Â } 358Â 364Â inline bool connected() const
365Â { 366Â return !!get_handle(); 367Â } 368Â 373Â inline bool check_abort() const 374Â { 375Â return
cancelled; 376Â } 377Â 386Â void set_command(void *handle, char *cmd, int size, char protType, unsigned
msgId); 387Â 389Â bool get_status(struct ProtStatus *status) const; 390Â 392Â bool
get_connection_info(struct ConnectInfo *info) const; 393Â 395Â void free_connection_info(struct ConnectInfo
*info) const; 396Â 398Â void set_com_profile(const char *file) const; 399Â 404Â bool trusted_connection();
405Â 412Â bool get_tcp_info(struct TcpInfo *info); 413Â 420Â bool get_uds_info(struct UdsInfo *info); 421Â
426Â void *get_handle() const; 427Â 430Â char get_protocol_type() const; 431Â 446Â bool
isConnectionThread() const; 447Â 455Â bool isMainConnectionThread() const; 456Â 463Â int select(int
comInterfaces, char **ComFileName); 464Â 467Â void reset(); 468Â }; 469Â 472Â class madk_pp_protBusyLock
473Â { 474Â madk_pp_prot *m_proto; 475Â bool m_locked; 476Â 477Â // disable copy constructor and assign
operator 478Â madk_pp_protBusyLock(const madk_pp_protBusyLock&); 479Â madk_pp_protBusyLock& operator=(const
madk_pp_protBusyLock&); 480Â #if __cplusplus >= 201103L // since C++11 also forbid usage of move 481Â
madk_pp_protBusyLock(const madk_pp_protBusyLock&&); 482Â madk_pp_protBusyLock&
operator=(madk_pp_protBusyLock&&); 483Â #endif 484Â 485Â public: 490Â madk_pp_protBusyLock(bool cmd_ctx =
true) 491Â { 492Â m_proto = madk_pp_prot::getInstance(); 493Â m_locked = m_proto->set_busy(true, cmd_ctx);
494Â } 496Â virtual ~madk_pp_protBusyLock() 497Â { 498Â unlock(); 499Â } 502Â void unlock() 503Â { 504Â
if (m_locked) 505Â { 506Â m_proto->set_busy(false); 507Â m_locked = false; 508Â } 509Â } 512Â bool
locked() const 513Â { 514Â return m_locked; 515Â } 516Â }; 517Â 518Â #endif
```